

# 面向移动与边缘设备的 人工智能系统

Al Systems towards Mobile and Edge Devices

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### Outline

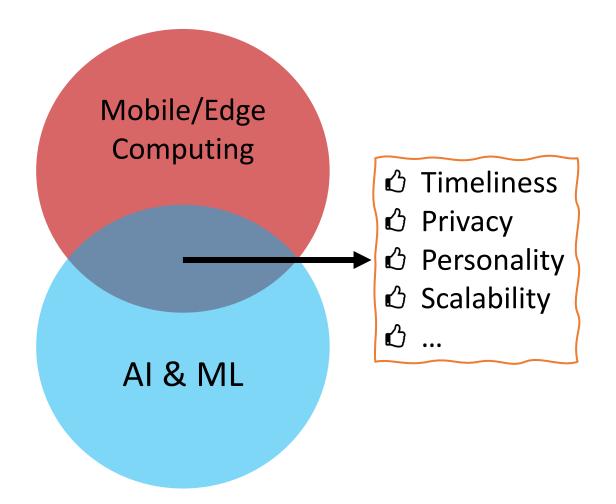


- Edge Intelligence: What and Why?
  - A system software perspective

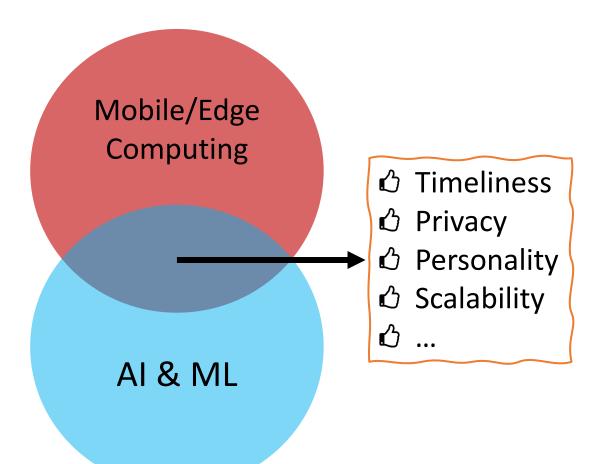
- Two pieces of my research on AloT cameras
  - Zero-streaming Cameras (full paper under review, MobiCom'20 Demo)
  - Autonomous Cameras (MobiSys'20)

# Edge + Al





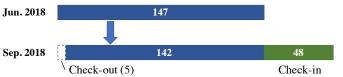
## Edge + Al



#### Some random evidences:







On Google Play, DL apps have increased by 27% in 3<sup>rd</sup> quarter of 2018

• Statistics from our WWW'19 paper

#### A Berkeley View of Systems Challenges for AI

Ion Stoica, Dawn Song, Raluca Ada Popa, David Patterson, Michael W. Mahoney, Randy Katz, Anthony D. Joseph, Michael Jordan, Joseph M. Hellerstein, Joseph Gonzalez, Ken Goldberg, Ali Ghodsi, David Culler, Pieter Abbeel\*

R9: Cloud-edge systems. Today, many AI applications such as speech recognition and language translation are deployed in the cloud. Going forward we expect a rapid increase in AI systems that span edge devices and the cloud. On one hand, AI systems which

#### More DL frameworks are built for edges!

• TFLite, ncnn, mnn, Mace, etc...

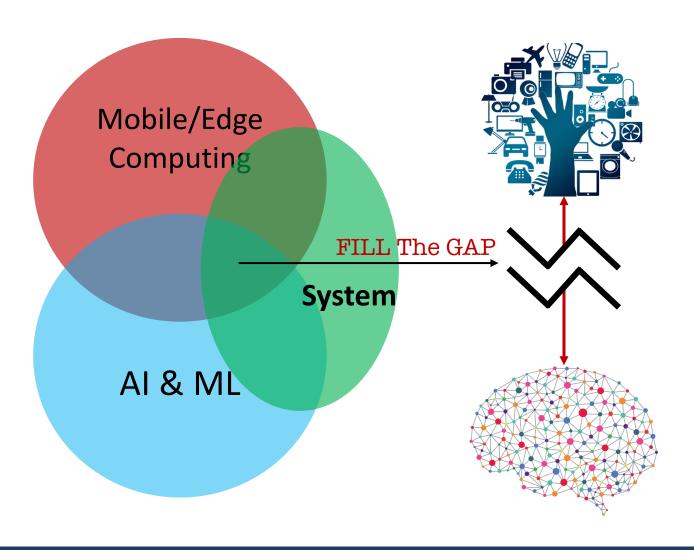
2016

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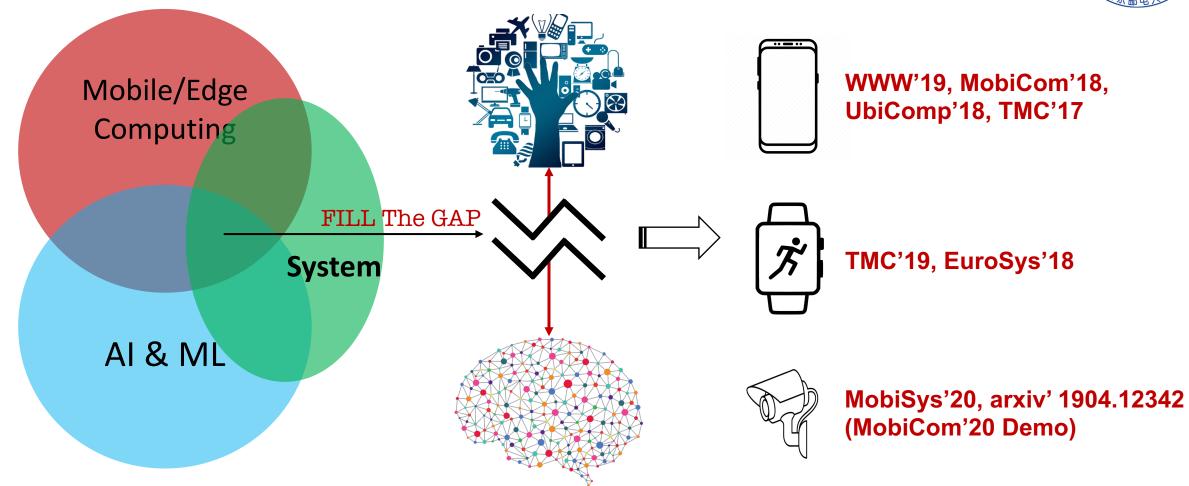
# Edge + AI + System





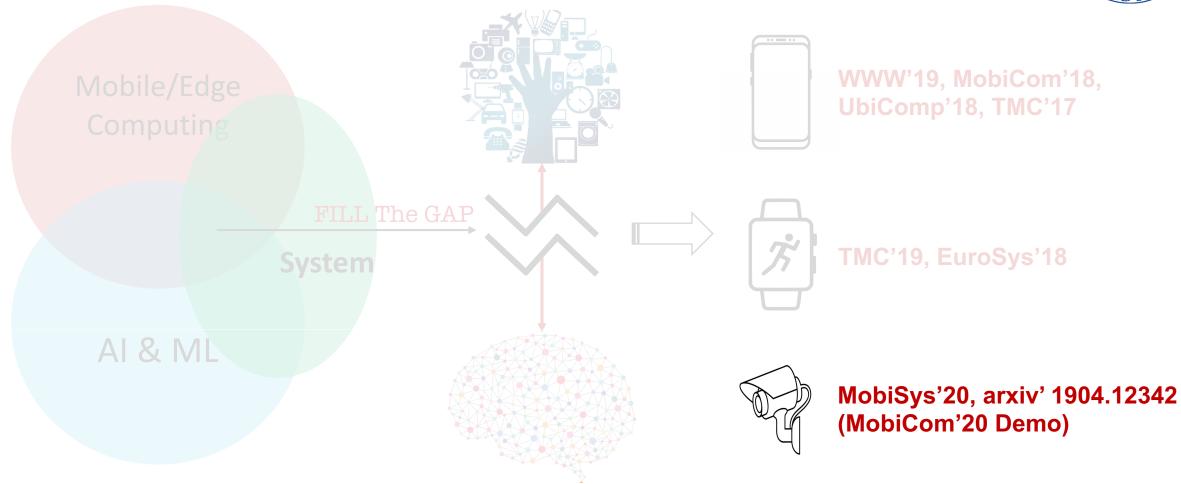
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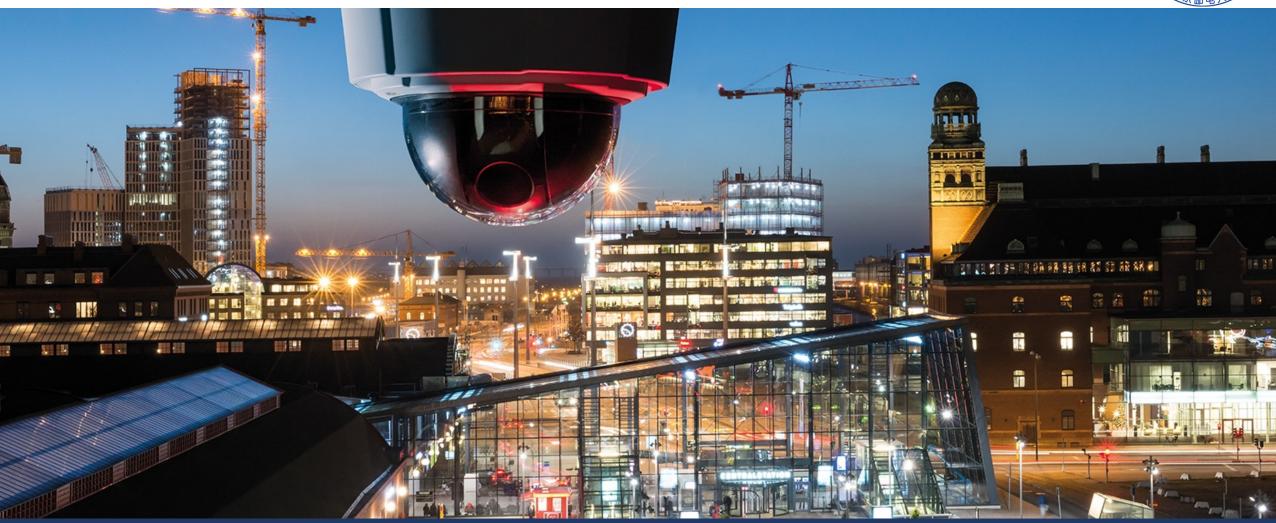


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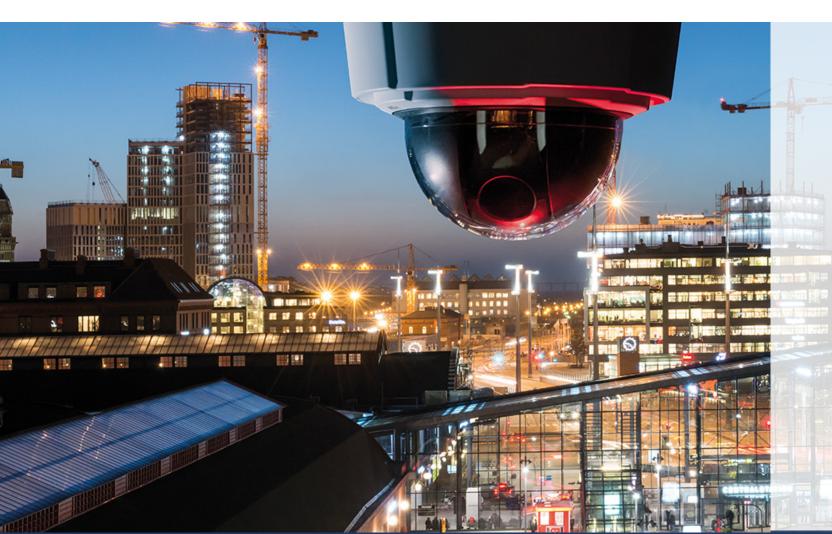












Video Surveillance Market Size is Expected to Reach USD 144.85 Billion by 2027 - Valuates Reports

In 2017



98 million

network surveillance cameras will be shipped globally through professional sales channels



29 million

HD CCTV surveillance cameras will be shipped globally through professional sales channels



400,000

body worn cameras will be shipped to law enforcement agencies globally

#### MORE CAMERAS IN MORE PLACES

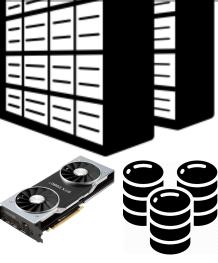
All respondents either have video surveillance installed today (95%) or plan to install it in the next 12 months (5%). The largest total number of cameras reported by one respondent was 25.000. Indeed, the average number of cameras per network has increased almost 70%, from around 2.900 cameras to 4.900 cameras between 2015 and 2018. In the latest edition of the survey, 20%





#### Traditional approach: cloud-centric paradigm

- [SIGCOMM'20] Reducto, [SOSP'19] Nexus, [OSDI'18] Focus, etc
- Cameras are just data sources or with dumb intelligence



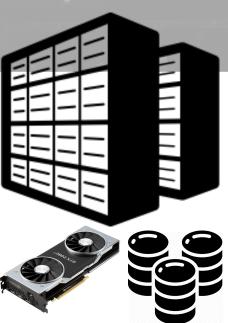




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Our approach: camera-centric paradigm



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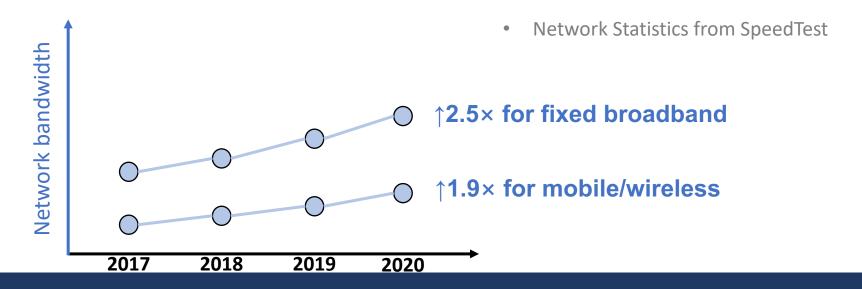
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- Motivations
  - 1. Most videos are cold: a case study from PKU campus
    - ☐ More than 1,000 cameras deployed
    - ☐ Only <0.005% video and <2% cameras are eventually queried within 6 months

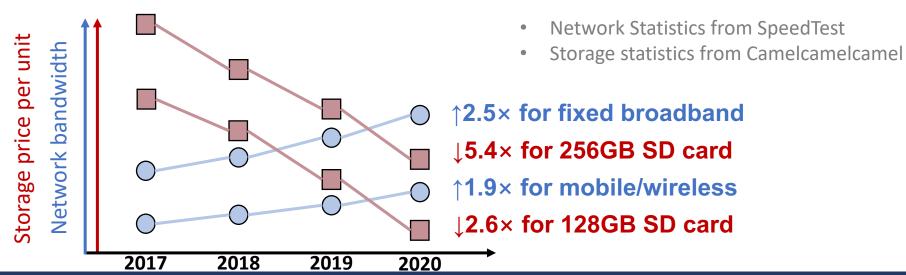


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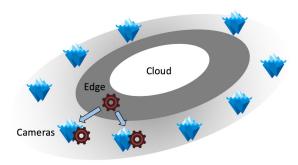


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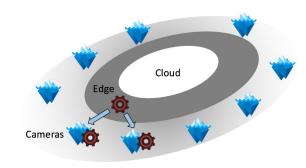
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  - Ingestion time: stored to local storage
  - Query time: camera-cloud collaboration



Cameras capture videos & keep silence
Only respond to queries



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- Challenge: accelerating video query
  - Limited BW is the bottleneck: the order matters

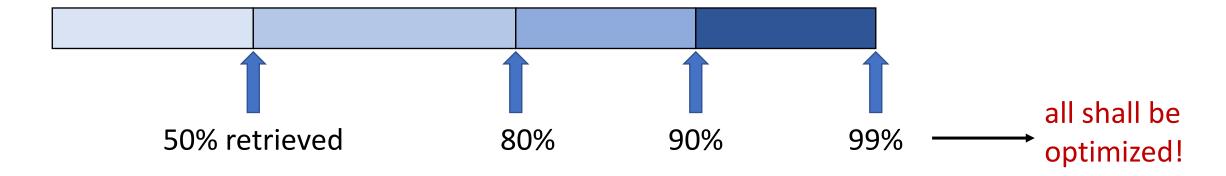


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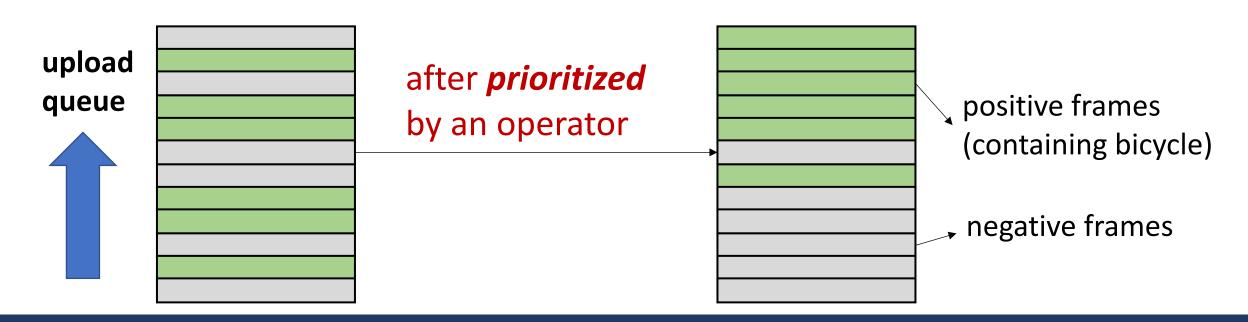
- Key idea: exploratory query with online refinement
  - Deliver early results to users AFAP & keep refinement

Q: retrieve all images with bicycles?



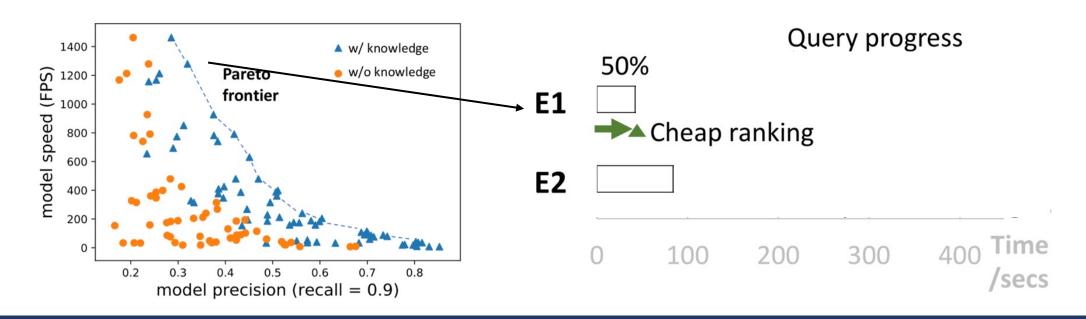


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  - Operator: specialized (for query) NNs, on-the-fly trained



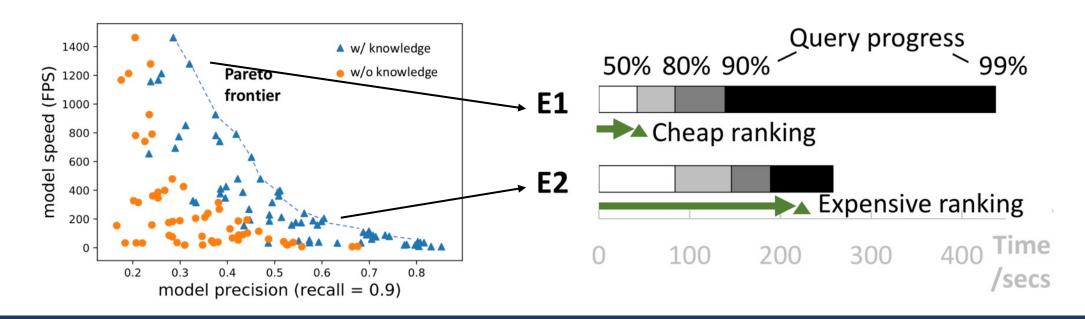


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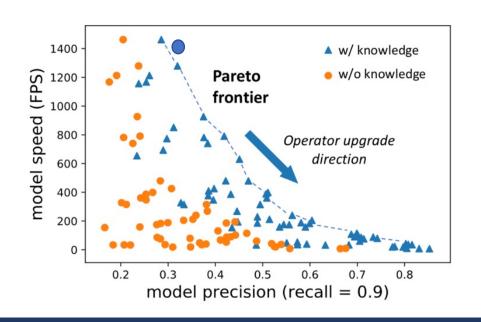


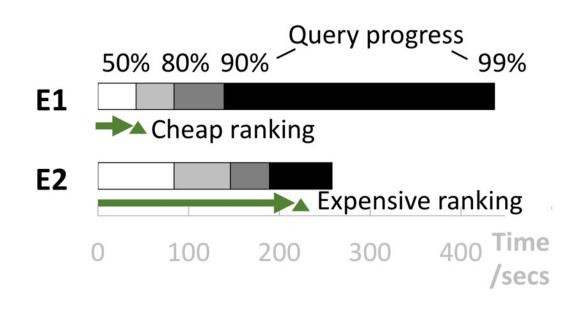
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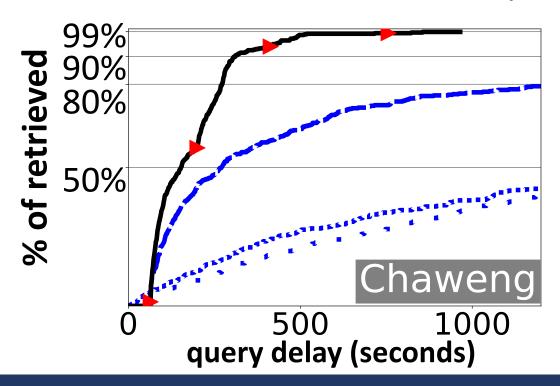




## Highlights of experiment results



- On 15 real videos (720 hrs in total), two representative camera hardware, 3 query types
- We are 4-30X faster than competitive alternatives

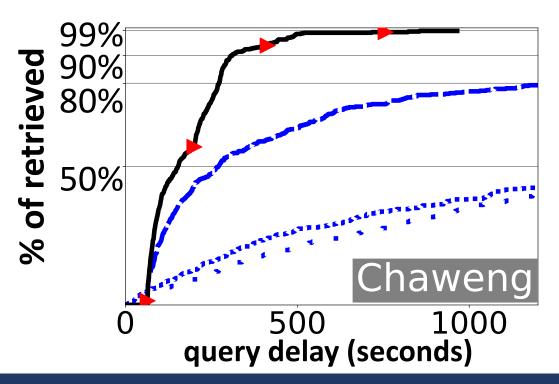


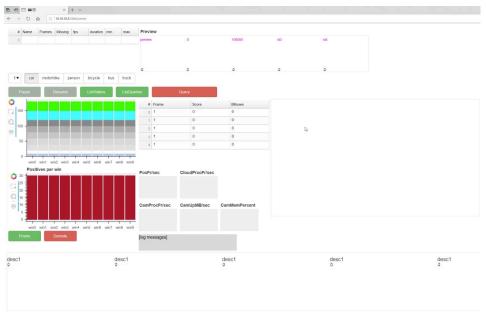
Example: How fast we can retrieve frames with bicycles to users?

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A web-based demo

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## **Autonomous Camera**

- Busy cross roads
- Retailing store
- Sports stadium
- Parking lots

• ...













- Construction sites
- Cattle farms
- Highways
- Wildlifes
- •

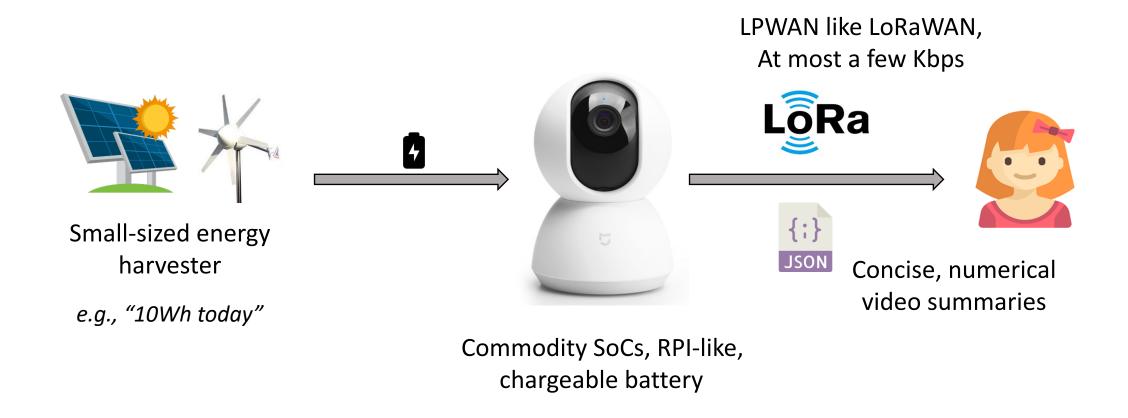
Urban, residential areas

Rural, off-grid areas

### **Autonomous Camera**



Energy-independent and Compute-independent



#### Autonomous Camera



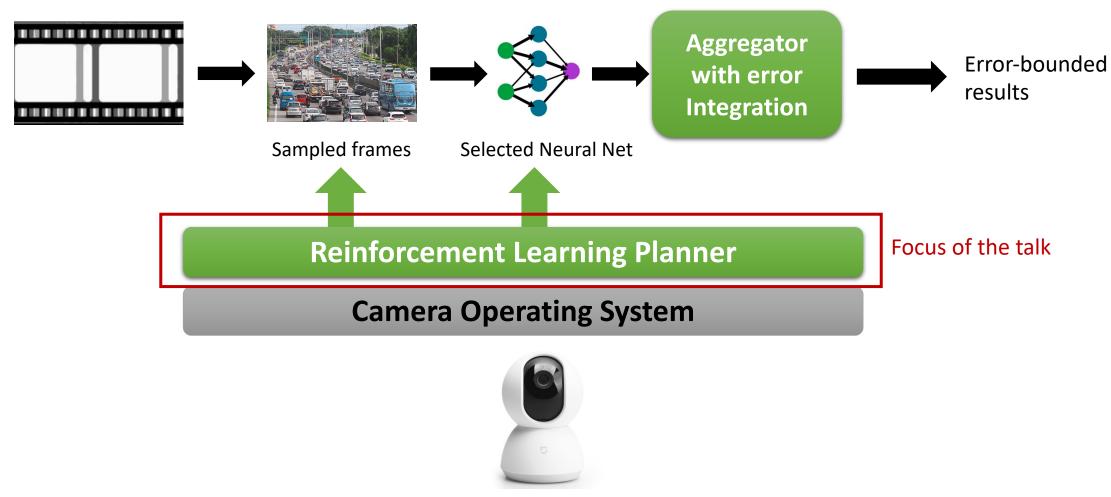
Energy-independent and Compute-independent

- Target query: summarize video based on time windows
  - With bounded error, e.g., confidence interval (CI).

- The central problem: planning constrained energy (an energy budget)
  - O Not enough to run the most expensive NN on every frame!
  - Key trade-offs: frame sampling and NN selection

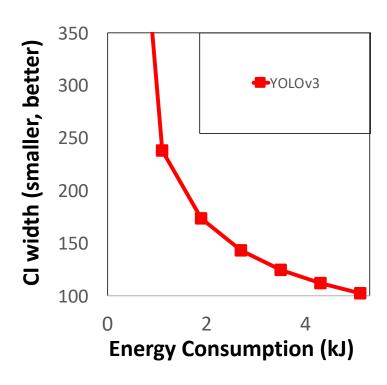
### Elf Runtime for autonomous camera







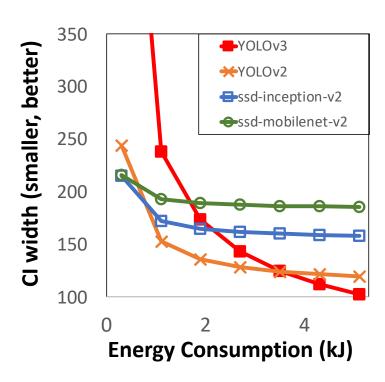
What's the best sampling rate and NN for a window?



Energy Consumption = E(NN) \* frame num



What's the best sampling rate and NN for a window? – No silver bullet

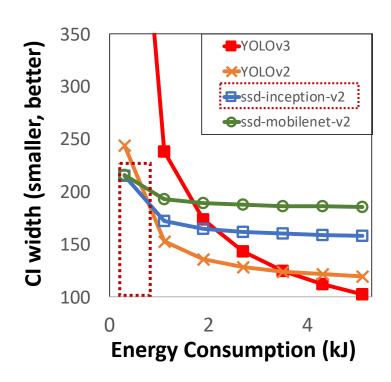


Energy Consumption = E(NN) \* frame\_num

NN Counters	Input	mAP	Energy
Y0L0v3 (Golden, GT) [85]	608x608	33.0	1.00
Y0L0v2 [84]	416x416	21.6	0.22
faster rcnn inception-v2[86]	300x300	28.0	0.40
ssd inception-v2[68]	300x300	24.0	0.08
ssd mobilenet-v2[88]	300x300	22.0	0.05
ssdlite mobilenet-v2[88]	300x300	22.0	0.04



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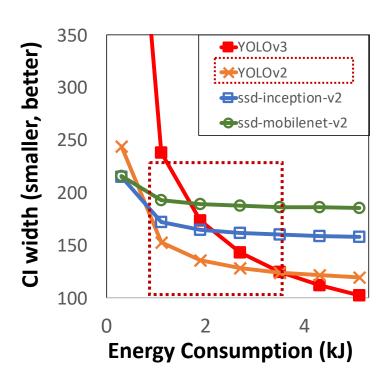


When energy is low: cheaper NNs win

Bottlenecked by sampling error (frame quantity)



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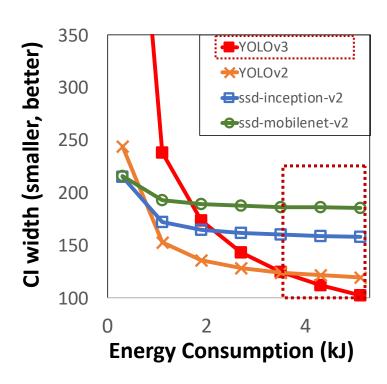


When energy is low: cheaper NNs win

- Bottlenecked by sampling error (frame quantity)
  When energy is high: more accurate NNs win
- Bottlenecked by NN error (frame quality)



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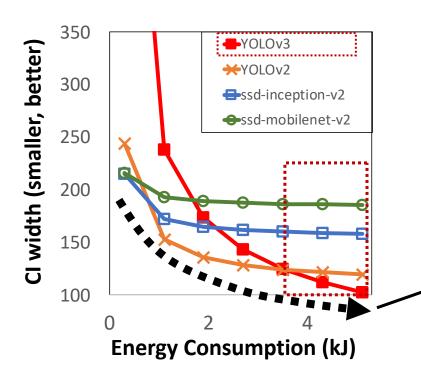


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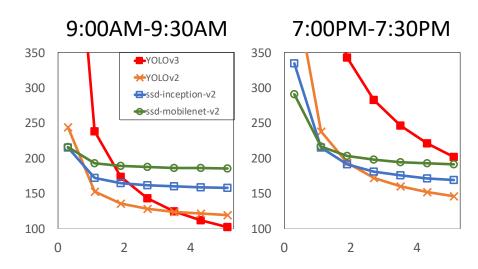
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**Energy/CI front:** the combination of all "optimal" decisions with varied energy



What's the best sampling rate and NN for a window? – No silver bullet



Different windows have different energy/CI fronts

When energy is low: cheaper NNs win

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**Energy/CI front:** the combination of all "optimal" decisions with varied energy

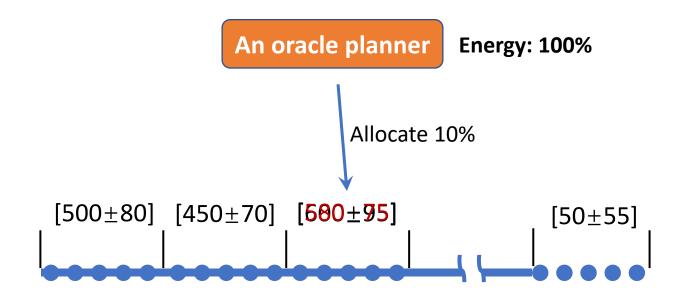
Depends on the video characteristics



- An Oracle Planner: best performance but unrealistic
  - knows all energy/CI fronts



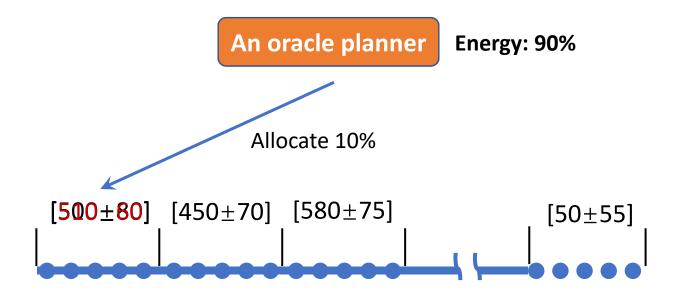
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A greedy approach: giving energy to the window with the most benefit (i.e., CI width reduction).



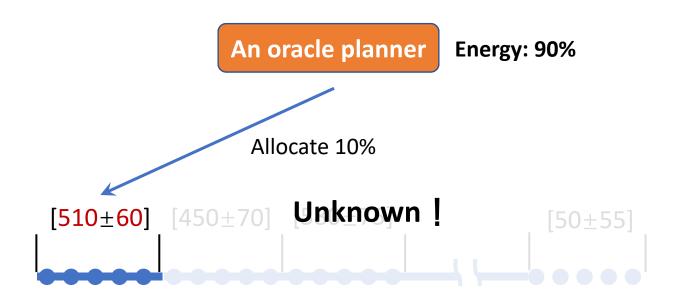
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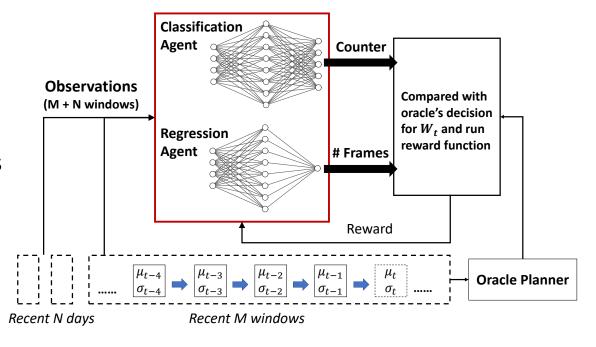
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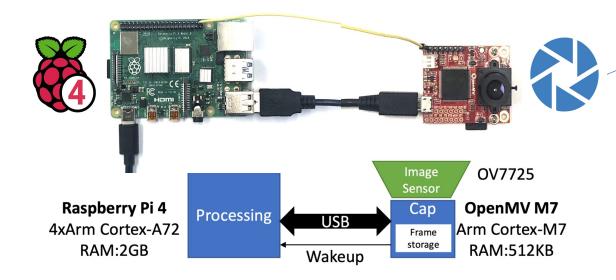
- An Oracle Planner: best performance but unrealistic
  - knows all energy/CI fronts
- A learning-based planner: imitating the oracle planner
  - basis: reinforcement learning
  - rationale: daily and temporal patterns
  - offline training -> online prediction
    - Two agents: NN selection and # of frames
    - Observations: knowledge of past windows
    - Penalty: deviation from oracle's decision



## Highlights of experiment results



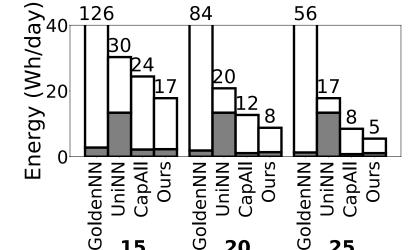
• Implementation: heterogeneous hardware



reduce energy for image capture

84

126



Mean CI Width

- Evaluated on over 1,000-hrs video
  - Saves up to 10X energy (to meet accuracy)

56

## Takeaways



- Edge devices shall/will be intelligent by themselves
  - A trend of decentralization...
  - Good system support is badly needed!

- AloT cameras are the next promising platform for edge intelligence
  - They can be zero-streaming, or even autonomous!
  - A brand new vision: <u>camera-as-a-service</u> (under major revison of IEEE Pervasive Computing)